# COMP3610/6361 <br> Principles of Programming Languages 

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## Section 19

## Concurrency

## Concurrency and Distribution

so far we concentrated on semantics for sequential computation but the world is not sequential. . .

- hardware is intrinsically parallel
- multi-processor architectures
- multi-threading (perhaps on a single processor)
- networked machines


## Problems

aim: languages that can be used to model computations that execute in parallel and on distributed architectures

## problems

- state-spaces explosion with $n$ threads, each of which can be in 2 states, the system has $2^{n}$ states
- state-spaces become complex
- computation becomes nondeterministic
- competing for access to resources may deadlock or suffer starvation
- partial failure (of some processes, of some machines in a network, of some persistent storage devices)
- communication between different environments
- partial version change
- communication between administrative regions with partial trust (or, indeed, no trust)
- protection against malicious attack

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## Problems

## this course can only scratch the surface

concurrency theory is a broad and active field for research

## Process Calculi

- Observation (1970s): computers with shared-nothing architectures communicating by sending messages to each other would be important
[Edsger W. Dijkstra, Tony Hoare, Robin Milner, and others]
- Hoare's Communicating Sequential Processes (CSP) is an early and highly-influential language that capture a message passing form of concurrency
- many languages have built on CSP including Milner's CCS and $\pi$-calculus, Petri nets, and others


## IMP - Parallel Commands

we extend our while-language that is based on aexp, bexp and com

## Syntax

$$
\text { com }::=\ldots \text { | com || com }
$$

Semantics
(par1) $\frac{\left\langle c_{0}, s\right\rangle \longrightarrow\left\langle c_{0}^{\prime}, s^{\prime}\right\rangle}{\left\langle c_{0} \| c_{1}, s\right\rangle \longrightarrow\left\langle c_{0}^{\prime} \| c_{1}, s^{\prime}\right\rangle}$
(par2) $\frac{\left\langle c_{1}, s\right\rangle \longrightarrow\left\langle c_{1}^{\prime}, s^{\prime}\right\rangle}{\left\langle c_{0} \| c_{1}, s\right\rangle \longrightarrow\left\langle c_{0} \| c_{1}^{\prime}, s^{\prime}\right\rangle}$

## IMP - Parallel Commands

## Typing

(thread)

$$
\frac{\Gamma \vdash c: \text { unit }}{\Gamma \vdash c: \text { proc }}
$$

(par ) $\frac{\Gamma \vdash c_{0}: \text { proc } \quad \Gamma \vdash c_{1}: \text { proc }}{\Gamma \vdash c_{0} \| c_{1}: \text { proc }}$

## Parallel Composition: Design Choices

- threads do not return a value
- threads do not have an identity
- termination of a thread cannot be observed within the language
- threads are not partitioned into 'processes' or machines
- threads cannot be killed externally


## Asynchronous Execution

- semantics allow interleavings

$$
\begin{aligned}
&\langle l:=1 \| l:=2,\{l \mapsto 0\}\rangle\langle\text { skip } \| l:=2,\{l \mapsto 1\}\rangle \longrightarrow\langle\text { skip } \| \text { skip },\{l \mapsto 2\}\rangle \\
&\langle l:=1 \| \text { skip },\{l \mapsto 2\}\rangle \longrightarrow\langle\text { skip } \| \text { skip },\{l \mapsto 1\}\rangle
\end{aligned}
$$

- assignments and dereferencing are atomic

$$
\begin{aligned}
& \langle l:=N \| l:=2,\{l \mapsto 0\}\rangle \longrightarrow\langle\text { skip } \| l:=2,\{l \mapsto N\}\rangle \longrightarrow\langle\text { skip } \| \text { skip },\{l \mapsto 2\}\rangle \\
& \text { for } N=3498734590879238429384 .
\end{aligned}
$$

(not something as the first word of one and the second word of the other)

## Asynchronous Execution

- there interleaving in $(l:=e) \| e^{\prime}$



## Morals

- combinatorial explosion
- drawing state-space diagrams only works for really tiny examples
- almost certainly the programmer does not want all those 3 outcomes to be possible
- complicated/impossible to analyse without formal methods


## Parallel Commands - Nondeterminism

## Semantics

(par1) $\frac{\left\langle c_{0}, s\right\rangle \longrightarrow\left\langle c_{0}^{\prime}, s^{\prime}\right\rangle}{\left\langle c_{0} \| c_{1}, s\right\rangle \longrightarrow\left\langle c_{0}^{\prime} \| c_{1}, s^{\prime}\right\rangle}$
(par2 ) $\frac{\left\langle c_{1}, s\right\rangle \longrightarrow\left\langle c_{1}^{\prime}, s^{\prime}\right\rangle}{\left\langle c_{0} \| c_{1}, s\right\rangle \longrightarrow\left\langle c_{0} \| c_{1}^{\prime}, s^{\prime}\right\rangle}$
(+maybe rules for termination)

- study of nondeterminism
- || is not a partial function from state to state; big-step semantics needs adaptation
- can we achieve parallelism by nondeterministic interleaving
- communication via shared variable


# Study of Parallelism (or Concurrency) 

includes

Study of Nondeterminism

## Dijkstra's Guarded Command Language (GCL)

- defined by Edsger Dijkstra for predicate transformer semantics
- combines programming concepts in a compact/abstract way
- simplicity allows correctness proofs
- closely related to Hoare logic


## GCL - Syntax

- arithmetic expressions: aexp
(as before)
- Boolean expressions: bexp (as before)
- Commands:

$$
\begin{aligned}
\text { com }::= & \text { skip } \mid \text { abort }|l:=\operatorname{aexp}| \text { com } ; \text { com } \mid \\
& \text { if gc fi } \mid \text { do gc od }
\end{aligned}
$$

- Guarded Commands:

$$
\begin{aligned}
\text { gc }::= & \text { bexp } \rightarrow \text { com } \mid \\
& \text { gc } \rrbracket \text { gc }
\end{aligned}
$$

## GCL - Semantics

- assume we have semantic rules for bexp and aexp (standard) we skip the deref-operator from now on
- assume a new configuration fail


## Guarded Commands

(pos) $\quad \frac{\langle b, s\rangle \longrightarrow\langle\text { true }, s\rangle}{\langle b \rightarrow c, s\rangle \longrightarrow\langle c, s\rangle} \quad$ (neg) $\quad \frac{\langle b, s\rangle \longrightarrow\langle\text { false }, s\rangle}{\langle b \rightarrow c, s\rangle \longrightarrow \text { fail }}$
(par1) $\frac{\left\langle g c_{0}, s\right\rangle \longrightarrow\left\langle c, s^{\prime}\right\rangle}{\left\langle g c_{0} \square g c_{1}, s\right\rangle \longrightarrow\left\langle c, s^{\prime}\right\rangle} \quad$ (par2) $\quad \frac{\left\langle g c_{1}, s\right\rangle \longrightarrow\left\langle c, s^{\prime}\right\rangle}{\left.\left\langle g c_{0}\right] g c_{1}, s\right\rangle \longrightarrow\left\langle c, s^{\prime}\right\rangle}$
(par3) $\frac{\left\langle g c_{0}, s\right\rangle \longrightarrow \text { fail } \quad\left\langle g c_{1}, s\right\rangle \longrightarrow \text { fail }}{\left.\left\langle g c_{0}\right] g c_{1}, s\right\rangle \longrightarrow \text { fail }}$

## GCL - Semantics

## Commands

- skip and sequencing ; as before (can drop determinacy)
- abort has no rules
(cond)

$$
\frac{\langle g c, s\rangle \longrightarrow\left\langle c, s^{\prime}\right\rangle}{\langle i \mathbf{i f} g c \mathbf{f i}, s\rangle \longrightarrow\left\langle c, s^{\prime}\right\rangle}
$$

(loop1)

$$
\frac{\langle g c, s\rangle \longrightarrow \text { fail }}{\langle\mathbf{d o} g c \mathbf{0 d}, s\rangle \longrightarrow\langle\langle s\rangle\rangle}{ }^{\dagger}
$$

(loop2) $\frac{\langle g c, s\rangle \longrightarrow\left\langle c, s^{\prime}\right\rangle}{\langle\mathbf{d o} g c \mathbf{0 d}, s\rangle \longrightarrow\left\langle c ; \mathbf{d o} g c \text { od }, s^{\prime}\right\rangle}$
${ }^{\dagger}$ new notation: behaves like skip

## Processes

$$
\text { do } b_{1} \rightarrow c_{1} \rrbracket \cdots \rrbracket b_{n} \rightarrow c_{n} \text { od }
$$

- form of (nondeterministically interleaved) parallel composition
- each $c_{i}$ occurs atomically (uninterruptedly), provided $b_{i}$ holds each time it starts

Some languages support/are based on GCL

- UNITY (Misra and Chandy)
- Hardware languages (Staunstrup)


## GCL - Examples

- compute the maximum of $x$ and $y$
if

$$
\begin{aligned}
& x \geq y \rightarrow \max :=x \\
& y \geq x \rightarrow \max :=y
\end{aligned}
$$

fi

- Euclid's algorithm
do

$$
\begin{aligned}
& x>y \rightarrow x:=x-y \\
& y>x \rightarrow y:=y-x
\end{aligned}
$$

od

## GCL and Floyd-Hoare logic

guarded commands support a neat Hoare logic and decorated programs

## Hoare triple for Euclid

$$
\{x=m \wedge y=n \wedge m>0 \wedge n>0\}
$$

Euclid

$$
\{x=y=\operatorname{gcd}(m, n)\}
$$

## Proving Euclid's Algorithm Correct

- recall $\operatorname{gcd}(m, n)|m, \operatorname{gcd}(m, n)| n$ and

$$
\ell|m, n \Rightarrow \ell| \operatorname{gcd}(m, n)
$$

- invariant: $\operatorname{gcd}(m, n)=\operatorname{gcd}(x, y)$
- key properties:

$$
\begin{aligned}
\operatorname{gcd}(m, n) & =\operatorname{gcd}(m-n, n) & & \text { if } m>n \\
\operatorname{gcd}(m, n) & =\operatorname{gcd}(m, n-m) & & \text { if } n>m \\
\operatorname{gcd}(m, m) & =m & &
\end{aligned}
$$

## Synchronised Communication

- communication by "handshake"
- possible exchange of value (localised to process-process (CSP) or to a channel (CCS))
- abstracts from the protocol underlying coordination
- invented by Hoare (CSP) and Milner (CCS)


## Extending GCL

- allow processes to send and receive values on channels $\alpha!a$ evaluate expression $a$ and send value on channel $\alpha$
$\alpha ? x \quad$ receive value on channel $\alpha$ and store it in $x$
- all interactions between parallel processes is by sending / receiving values on channels
- communication is synchronised (no broadcast yet)
- allow send and receive in commands $c$ and in guards $g$ :

$$
\text { do } y<100 \wedge \alpha ? x \rightarrow \alpha!(x \cdot x) \| y:=y+1 \text { od }
$$

## Extending GCL - Semantics

transitions may carry labels when possibility of interaction

$$
\begin{array}{cl}
\xrightarrow[{\langle\alpha ? x, s\rangle \xrightarrow{\alpha ? n}\langle\langle s+\{x \mapsto n\}\rangle}\rangle]{ } & \stackrel{\langle a, s\rangle \longrightarrow\langle n, s\rangle}{\langle\alpha!a, s\rangle \xrightarrow{\alpha!n}\langle\langle s\rangle\rangle} \\
\frac{\left\langle c_{0}, s\right\rangle \xrightarrow{\lambda}\left\langle c_{0}^{\prime}, s^{\prime}\right\rangle}{\left\langle c_{0} \| c_{1}, s\right\rangle \xrightarrow{\lambda}\left\langle c_{0}^{\prime} \| c_{1}, s^{\prime}\right\rangle} & \text { (+ symmetric) } \\
\begin{array}{c}
\left\langle c_{0}, s\right\rangle \xrightarrow{\alpha ? n}\left\langle c_{0}^{\prime}, s^{\prime}\right\rangle \quad\left\langle c_{1}, s\right\rangle \xrightarrow{\alpha!n}\left\langle c_{1}^{\prime}, s\right\rangle \\
\left\langle c_{0} \| c_{1}, s\right\rangle \longrightarrow\left\langle c_{0}^{\prime} \| c_{1}^{\prime}, s^{\prime}\right\rangle \\
\text { (+ symmetric) } \\
\frac{\langle c, s\rangle \xrightarrow{\lambda}\left\langle c^{\prime}, s^{\prime}\right\rangle}{\langle c \backslash \alpha, s\rangle \xrightarrow{\lambda}\left\langle c^{\prime} \backslash \alpha, s^{\prime}\right\rangle} \lambda \notin\{\alpha ? n, \alpha!n\}
\end{array}
\end{array}
$$

$\lambda$ may be the empty label

## Examples

- forwarder:

$$
\text { do } \alpha ? x \rightarrow \beta!x \text { od }
$$

- buffer of capacity 2 :

$$
\begin{aligned}
& \text { ( do } \alpha \text { ? } x \rightarrow \beta!x \text { od } \\
& \| \text { do } \beta ? x \rightarrow \gamma!x \text { od }) \backslash \beta
\end{aligned}
$$

## External vs Internal Choice

the following two processes are not equivalent w.r.t. deadlock capabilities

$$
\begin{aligned}
& \text { if }\left(\text { true } \wedge \alpha ? x \rightarrow c_{0}\right) \square\left(\text { true } \wedge \beta ? x \rightarrow c_{1}\right) \mathbf{f i} \\
& \text { if } \left.\left(\text { true } \rightarrow \alpha ? x ; c_{0}\right)\right]\left(\text { true } \rightarrow \beta ? x ; c_{1}\right) \mathbf{f i}
\end{aligned}
$$


[^0]:    - ..

